

STATISTICAL & NUMERICAL METHODS
EXAM
11 April 2014

DIRECTIONS: ALLOW 3 HOURS. WRITE YOUR NAME AND STUDENT NUMBER AT THE TOP OF EVERY PAGE OF YOUR SOLUTIONS. Please explain clearly all of the steps that you used to derive a result. Please make certain that your handwriting is readable to someone besides yourself.

1. Answer briefly (at least 4–5 sentences) the following questions: **10 points/question**
 - (a) Describe two methods for finding the root of a 1D non-linear real function. Mention the drawbacks and advantages of each method.
 - (b) Describe why many data points are needed to determine their underlying probability distribution function.
 - (c) Suppose you have a model that has several parameters, A , B , C , and D , and that you can estimate $\text{prob}(A, B, C, D|\{\text{data}\}, I)$. Name and describe the process by which you could determine $\text{prob}(B|\{\text{data}\}, I)$.
 - (d) Describe the basic assumptions of the least-squares method for fitting a model to data. Describe the use of the χ^2 statistic in the least-squares method. Describe (at least) two methods to determine the uncertainties (confidence intervals) of the inferred parameters of the model.
 - (e) Describe the difference between accuracy and precision, and relate these terms to random uncertainties and systematic uncertainties.
 - (f) You are given a function $Z = f(X, Y)$ and you know that X and Y have Gaussian probability distribution functions, with uncertainties σ_X and σ_Y , and that X and Y are independent. What is the variance σ_Z^2 of Z ? Determine σ_Z^2 when $Z = 3X + Y^2$.
 - (g) Describe how you would numerically find the value of an improper integral. Provide a few examples of such integrals. For those examples, describe the steps you would take and the algorithms you would use to find the solutions.

2. A derivation: **4 points/question**. Explain your steps clearly and show your work.
- (a) Write down Cox's product rule for the probabilities $\text{prob}(X, Y|I)$ and $\text{prob}(Y, X|I)$.
 - (b) Solve these two equations for $\text{prob}(X|Y, I)$. This is Bayes' theorem.
 - (c) Write the equation you derived in part (b) again, calling X the "hypothesis" and Y the "data". What is the name of each term on each side of this equation?
 - (d) Set $P = \text{prob}(X|Y, I)$. How would you determine the best estimate X_0 of X , given P ? How would you prove that X_0 is indeed the best estimate of X ?
 - (e) Describe the importance of Bayes' theorem for data analysis (no more than 3–4 sentences).
3. True/false questions – mark T for a true statement or F for a false statement on your exam paper: **1 point/question**
- (a) A spline is a 4th order polynomial.
 - (b) A Poisson distribution is an appropriate likelihood function for binned data when you know the expected signal in each bin.
 - (c) A Kolmogorov-Smirnov test is the appropriate test when comparing two distributions generated from binned data, for example when asking whether two luminosity functions have been drawn from the same distribution.
 - (d) The best estimate of a parameter drawn from a (one-dimensional) Gaussian distribution based on data with equal uncertainties is the mean of the individual data points.
 - (e) It is possible to use the rejection method to generate random numbers following a Gaussian distribution.
 - (f) The singular value decomposition method can be used to find the inverse of an $N \times M$ matrix.
 - (g) The spline method does not require knowledge of the 2nd derivative of the function to be interpolated.
 - (h) The leapfrog algorithm is time-reversible, and can be applied to find the solution to all types of ordinary differential equations.
 - (i) The appropriate prior for a location parameter is a constant in the allowed range.
 - (j) A binomial distribution is the appropriate probability distribution function when you know both the expected value and expected variance of an experiment.